

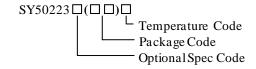
# **Application Note: SY50223**

Flyback controller For adapters or chargers

# **General Description**

SY50223 is a PWM/PFM controller with several features to enhance performance of Flyback converters that targeting at adapter or charger applications. It integrates a 700V MOSFET to decrease physical volume and drives Flyback controller in the Quasi-Resonant mode for higher efficiency and better EMI performance. SY50223 adopt burst mode control for improved efficiency and the output current is detected by internal primary detection technology to achieve more reliable Over Current Protection and Short Circuit Protection. The output voltage is achieved by secondary side control technology for good load and line regulation. SY50223 provides a fast internal HV start up circuit without consuming any standby power to achieve lowest no-load power consumption.

## **Ordering Information**



Ordering Number	Package type	Note
SY50223FAC	SO8	

## **Features**

- Quasi-Resonant (QR) mode operation: Valley turn-on of the primary MOSFET to achieve low switching losses
- Output current is monitored by primary detection for reliable Over Current Protection and Short Circuit Protection
- PWM/PFM conrol for higher average efficiency
- Burst mode control for low no-load power and efficiency
- HV start up circuit is used to reduce no-load power
- Maximum frequency limitation 125kHz
- Auto-Recovery OVP/OCP/SCP/OTP
- Integrated 700V MOSFET
- Compact package: SO8

## **Applications**

- AC/DC Adapters
- Battery Chargers
- Consumer Electronics
- Auxiliary power supplies

Recommended operating output power		
Products 90Vac~264Vac		
SY50223	12W	

# **Typical Applications**

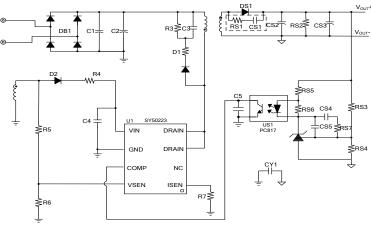
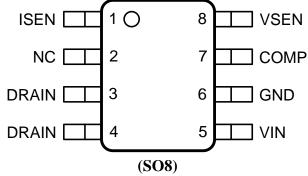


Fig.1 Schematic Diagram



# Pinout (Top view)



Top Mark: AJNxyz (device code: AJN, x=year code, y=week code, z=lot number code)

1	ISEN	Current sense pin. Connect this pin to the source of the primary switch.
2	NC	NC pin.
3	DRAIN	Drain of the internal power MOSFET.
4	DRAIN	Drain of the internal power MOSFET.
5	VIN	Power supply pin.
6	GND	Ground pin.
7	COMP	Feedback input pin. The PWM duty cycle is determined by voltage level into this pin. It's connected to a
/	COMI	optocoupler.
8	VSEN	Inductor current zero-crossing detection pin. This pin receives the auxiliary winding voltage by a
0	VSEN	resistor divider and detects the inductor current zero crossing point.

# **Block Diagram**

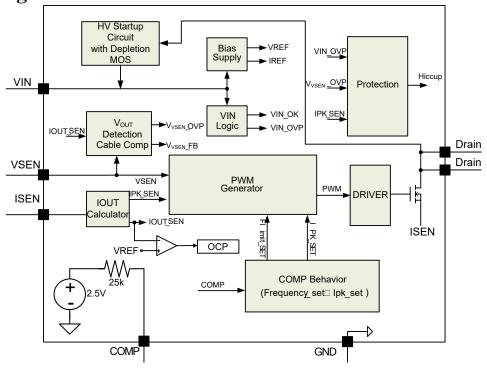


Fig.2 Block Diagram





<b>Absolute Maximum Ratings</b> (Note 1)	
VIN	
Supply Current I <sub>VIN</sub>	
ISEN, COMP	
VSEN	
DRAIN	
Power Dissipation, @ TA = 25°C SO8	1.1W
Package Thermal Resistance (Note 2)	
SO8, $\theta_{JA}$	125°C/W
SO8, $\theta_{JC}$	60°C/W
Junction Temperature Range	
Lead Temperature (Soldering, 10 sec.)	260°C
Storage Temperature Range	
<b>Recommended Operating Conditions</b>	
VIN	9V~17.5V
Junction Temperature Range	
Ambient Temperature Range	



# **Electrical Characteristics**

 $(V_{VIN} = 12V(Note 3), T_A = 25^{\circ}C \text{ unless otherwise specified})$ 

Parameter	Symbol	Test Conditions	Min	Тур	Max	Unit
Power Supply Section						
VIN operating range	V <sub>VIN_RANGE</sub>		9		17.5	V
VIN turn-on threshold	$V_{VIN\_ON}$		13.7	14.7	15.7	V
VIN turn-off threshold	V <sub>VIN_OFF</sub>		6.3	7	8.3	V
VIN OVP voltage	V <sub>VIN_OVP</sub>		17.5	18.5	19.5	V
HV start up current	I <sub>HV_ON</sub>			0.35		mA
HV leakage current	$I_{HV\_OFF}$			5		μΑ
Start up Current	$I_{ST}$	V <sub>VIN</sub> <v<sub>VIN_OFF</v<sub>		1.2		μΑ
Operating Current	I <sub>VIN</sub>	C <sub>L</sub> =100pF,f=100kHz		1		mA
Quiescent Current	IQ	V <sub>COMP</sub> =0	250	350	500	μA
Shunt current in OVP mode	I <sub>VIN_OVP</sub>	V <sub>VIN</sub> >V <sub>VIN_OVP</sub>		9		mA
Current Feedback Modulator Section	ion					
Internal reference voltage	V <sub>REF</sub>		0.414	0.42	0.426	V
ISEN Pin Section						
Cymnant limit mafanan aa yalta aa	V	$V_{FBV} < 0.4V$		0.7		V
Current limit reference voltage	V <sub>ISEN_MAX</sub>	V <sub>FBV</sub> >0.4V	0.9	1	1.1	V
Latch Voltage for ISEN	V <sub>ISEN_EX</sub>			2		V
VSEN Pin Section						
OVP voltage threshold	Vvsen_ovp		1.38	1.45	1.55	V
Integrated MOSFET Section						
Breakdown Voltage	$V_{\rm BV}$	V <sub>GS</sub> =0V,I <sub>DS</sub> =250μA	700			V
Switching Section						
Max ON Time	Ton_max	V <sub>COMP</sub> =2.5V, I <sub>ISEN</sub> =0		24		μs
Min ON Time	Ton_min			300	0	ns
Min OFF Time	T <sub>OFF_MIN</sub>		1.1	1.2	1.7	μs
Minimum switching period	TPERIOD_MIN		7	8	9	μs
COMP section	•				•	
Internal voltage bias	$V_{CVB}$			2.5		V
Sleep mode voltage ON threshold	V <sub>COMP_ON</sub>		0.3	0.4	0.5	V
Sleep mode voltage OFF threshold	V <sub>COMP_OFF</sub>		0.35	0.45	0.55	V
Internal pull-up resistor	R <sub>COMP</sub>			25		kΩ
Thermal Section	•				-	
Thermal Shutdown Temperature	$T_{SD}$			150		°C
N. 4 C: 1 1.1 ((41 1	. 16 .	D .: "	. 1	1 1	·	1

**Note 1**: Stresses beyond the "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only. Functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

**Note 2**:  $\theta_{JA}$  is measured in the natural convection at  $T_A = 25$ °C on a low effective single layer thermal conductivity test board of JEDEC 51-3 thermal measurement standard. Test condition: Device mounted on "2 x 2" FR-4 substrate PCB, 2oz copper, with minimum recommended pad on top layer and thermal via to bottom layer ground plane.

Note 3: Increase VIN pin voltage gradually higher than  $V_{VIN\_ON}$  voltage then turn down to 12V.



# **Operation**

SY50223 is a high performance Flyback controller with secondary side control and constant current and constant voltage regulation.

It integrates a 700V MOSFET to decrease physical volume.

In order to reduce the switching losses and improve EMI performance, Quasi-Resonant switching mode is applied, which means to turn on the integrated MOSFET at voltage valley; the start up current of the device is rather small(1.2 $\mu$ A typical) to reduce the standby power loss further and the maximum switching frequency is limited below 125kHz.

In order to improve the stability, the self-adaption compensation is applied.

SY50223 provides a fast internal HV start up circuit without consuming any standby power to achieve lowest no-load power consumption.

The output current is monitored by primary side detection technology, and the maximum output current can be programmed in Over Current Protection and Short Circuit Protection. In addition to SY50223 provides VIN Over Voltage Protection, Over Temperature Protection (OTP), Output voltage OVP protection(OVP) , VSEN pin short protection ,etc..

SY50223 can be applied in AC/DC adapters, Battery Chargers and other consumer electronics.

SY50223 is available with SO8 package.

# **Applications Information**

### Start up

To achieve better light load performance, HV start up design is added. After AC supply or DC BUS is powered on, the capacitor  $C_{VIN}$  across VIN and GND pin is charged up by internal HV start up circuit. Once  $V_{VIN}$  rises up to  $V_{VIN\_ON}$ , the internal blocks start to work.  $V_{VIN}$  will be pulled down by internal consumption of IC until the auxiliary winding of Flyback transformer could supply enough energy to maintain  $V_{VIN}$  above  $V_{VIN\_OFF}$ .

The whole start up procedure is divided into two sections shown in Fig.3.  $t_{STC}$  is the  $C_{VIN}$  charged up section, and

 $t_{STO}$  is the output voltage built-up section. The start up time  $t_{ST}$  composes of  $t_{STC}$  and  $t_{STO}$ , and usually  $t_{STO}$  is much smaller than  $t_{STC}$ .

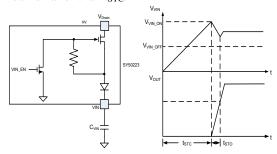


Fig.3 Start up

The start up capacitor C<sub>VIN</sub> is designed by rules below:

(a) Select  $C_{VIN}$  to obtain an ideal start up time  $t_{ST}$ , and ensure the output voltage is built up at one time.

$$C_{\text{VIN}} = \frac{(I_{\text{HV\_ON}} - I_{\text{HV\_OFF}} - I_{ST}) \times t_{\text{ST}}}{V_{\text{VIN ON}}} \tag{1}$$

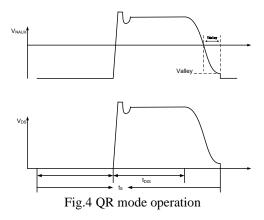
(b) If the  $C_{VIN}$  is not big enough to build up the output voltage at one time. Increase  $C_{VIN}$  until the ideal start up procedure is obtained.

#### Shut down

After AC supply or DC BUS is powered off, the energy stored in the BUS capacitor will be discharged. When the auxiliary winding of Flyback transformer can not supply enough energy to VIN pin,  $V_{\rm VIN}$  will drop down. Once  $V_{\rm VIN}$  is below  $V_{\rm VIN_OFF}$ , the IC will stop working.

### **Quasi-Resonant Operation(valley detection)**

QR mode operation provides low turn-on switching losses for Flyback converter.





The voltage across drain and source of the primary integrated MOSFET is reflected by the auxiliary winding of the Flyback transformer. VSEN pin detects the voltage across the auxiliary winding by a resistor divider. When the voltage on VSEN pin across zero, the MOSFET would be turned on after 400ns delay.

#### Output Voltage Control(CV control)

SY50223 is compatible with opto-coupler to achieve output voltage control, which is shown by Fig.5.

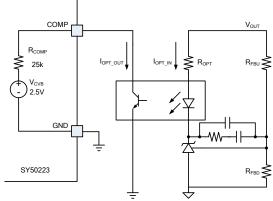


Fig.5 Output voltage feedback circuit

The OFF time of MOSFET is up to the valley detection of VSEN pin, and the ON time of MOSFET is a function of  $V_{\text{COMP}}$ , so the output power can be controlled by  $V_{\text{COMP}}$ .

SY50223 integrates an internal 2.5V voltage bias and  $25k\Omega$  resistor to interface the output of opto-coupler.  $V_{COMP}$  is in relation with the output current of the opto-coupler  $I_{OPT\_OUT}$  by

$$V_{COMP} = V_{CVB} - I_{OPT OUT} \times R_{COMP}$$
 (2)

 $R_{OPT}$  is the resistor across the output node and the anode of the opto-coupler. The selection of  $R_{OPT}$  is related with system loop stability, and higher loop gain of the system is achieved by smaller  $R_{OPT}$ .

At the same time, ROPT is designed by

$$V_{\text{CVB}} - I_{\text{OPT IN MAX}} \times \beta \times R_{\text{COMP}} < V_{\text{COMP ON}}$$
 (3)

Where  $\beta$  is the transfer ratio of the opto-coupler;  $I_{OPT\_IN\_MAX}$  is the maximum input current through the opto-coupler, which is limited by  $R_{OPT}$ .

### Output current detection by Primary side(CC control)

The output current is monitored by SY50223 with primary side detection technology. The maximum output current I<sub>OUT\_LIM</sub> can be regulated by:

$$I_{\text{OUT\_LIM}} = \frac{k_1 \times k_2 \times V_{\text{REF}} \times N_{\text{PS}}}{R_{\text{S}}} \ (4)$$

Where  $k_1$  is the output current weight coefficient, the value is 0.5;  $k_2$  is the output modification coefficient, the value is 1;  $V_{REF}$  is the internal reference voltage, the value is 0.42;  $N_{PS}$  is the turns ratio of the Flyback transformer;  $R_S$  is the current sense resistor.

 $k_1$ ,  $k_2$  and  $V_{REF}$  are all internal constant parameters,  $I_{OUT\_LIM}$  can be programmed by  $N_{PS}$  and  $R_S$ .

$$R_{s} = \frac{k_{1} \times k_{2} \times V_{REF} \times N_{PS}}{I_{OUT\_LIM}}$$
 (5)

When over current operation or short circuit operation happens.  $V_{COMP}$  will be pulled down, and the output current will be limited at  $I_{OUT\_LIM}$ . The V-I curve is shown as Fig.6.

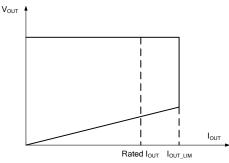


Fig.6 V-I curve

### Line regulation modification

The IC provides line regulation modification function to improve line regulation performance of the output current.

Due to the sample delay of ISEN pin and other internal delay, the output current increases with increasing input BUS line voltage. A small compensation voltage  $\Delta V_{\rm ISEN\_C}$  is added to ISEN pin during ON time to improve such performance. This  $\Delta V_{\rm ISEN\_C}$  is adjusted by the upper resistor of the divider connected to VSEN pin.



$$\Delta V_{ISEN\_C} = V_{BUS} \times \frac{N_{AUX}}{N_P} \times \frac{1}{R_{VSENU}} \times k_3 \quad (6)$$

Where  $R_{VSENU}$  is the upper resistor of the divider; k3 is an internal constant as the modification coefficient.

The compensation is mainly related with R<sub>VSENU</sub>, larger compensation is achieved with smaller R<sub>VSENU</sub>. Normally, R<sub>VSENU</sub> ranges from  $50k\Omega{\sim}150k\Omega$ .

#### **Short Circuit Protection (SCP)**

When the output is shorted to ground, the output voltage is clamped to zero. The voltage of the auxiliary winding is proportional to the output winding, so valley signal cannot be detected by VSEN. There are two cases, the one is without valley detection, MOSFET cannot be turned on until maximum off time is reached. Once VSEN>1V, if MOSFET is turned on with maximum off-time for 16 times continuously which can not detected valley, IC will be shut down and discharge the VIN voltage, then enter into hiccup mode. Otherwise, if VSEN cannot larger than 1V, this "valley detection protection method " will not be effective, IC will shut down until VIN is below  $V_{\rm VIN\_OF}$  and enter into hiccup mode.

When the output voltage is not low enough to disable valley detection in short condition, SY50223 will operate in CC mode until VIN is below  $V_{\text{VIN\_OFF}}$ .

In order to guarantee SCP function not effected by voltage spike of auxiliary winding, a filter resistor  $R_{\rm AUX}$  is needed.

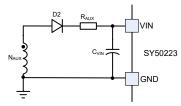


Fig. 7 Filter resistor  $R_{\text{AUX}}$ 

### **Output voltage OVP protection**

The secondary maximum voltage is limited by the SY50223. When the VSEN pin signal exceeds 1.45 V, SY50223 will stop switching and discharge the VIN voltage. Once  $V_{\text{VIN}}$  is below  $V_{\text{VIN}\_\text{OFF}}$ , the IC will shut down and then enter into hiccup mode.

#### **VSEN** pin short protection

The SY50223 has a protection against faults caused by a shorted VSEN pin or a shorted pull-down resistor. During

start-up, the voltage on the VSEN pin is monitored. In normal situations, the voltage on the VSEN pin reaches the sense protection trigger level. When the VSEN voltage does not reach this level, the VSEN pin is shorted and the protection is activated. The IC stops switching and discharge the VIN voltage. Once  $V_{\rm VIN}$  is below  $V_{\rm VIN\_OFF}$ , the IC will shut down and then enter into hiccup mode. In order to ensure reliable detection, the pull-down resistor should larger than  $2k\Omega$ .

#### **ISEN Pin Latch Protection**

The ISEN pin voltage is limited by the SY50223. When the ISEN pin signal exceeds 2V, SY50223 will stop switching and discharge the VIN voltage. Once VVIN is below  $V_{\text{VIN\_OFF}}$ , the IC will shut down and then enter into hiccup mode.

#### **Power Design**

A few applications are shown as below.

Products	Input range	Output		Temperature rise
	90Vac~264Vac	10W	5V/2.0A	40℃
SY50223	90Vac~264Vac	12W	5V/2.4A	60℃
	90Vac~264Vac	12W	12V/1A	50°C

The test is operated in natural cooling condition at  $25 \,^{\circ}\mathbb{C}$  ambient temperature.

# **Power Device Design**

### **Diode**

When the operation condition is with maximum input voltage and full load, the voltage stress of secondary power diode is maximized.

$$V_{D\_R\_MAX} = \frac{\sqrt{2}V_{AC\_MAX}}{N_{PS}} + V_{OUT}$$
 (7)

Where  $V_{AC\_MAX}$  is maximum input AC RMS voltage;  $N_{PS}$  is the turns ratio of the Flyback transformer;  $V_{OUT}$  is the rated output voltage.

When the operation condition is with minimum input voltage and full load, the current stress of and power diode is maximized.

$$I_{D\_PK\_MAX} = N_{PS} \times I_{P\_PK\_MAX}$$
 (8)



$$I_{DAVG} = I_{OUT}$$
 (9)

Where  $I_{P\_PK\_MAX}$  is maximum primary peak current , which will be introduced later.

#### Transformer (NPS and LM)

 $N_{PS}$  is limited by the electrical stress of the integrated power MOSFET:

$$N_{PS} \le \frac{V_{MOS\_(BR)DS} \times 80\% - \sqrt{2}V_{AC\_MAX} - \Delta V_{S}}{V_{OUT} + V_{D\_F}}$$
(10)

Where  $V_{MOS\_(BR)DS}$  is the breakdown voltage of the integrated power MOSFET;  $V_{D\_F}$  is the forward voltage of secondary power diode;  $\Delta V_S$  is the overshoot voltage clamped by RCD snubber during OFF time.

In Quasi-Resonant mode, each switching period cycle  $t_S$  consists of three parts: current rising time  $t_1$ , current falling time  $t_2$  and quasi-resonant time  $t_3$  shown in Fig.8.

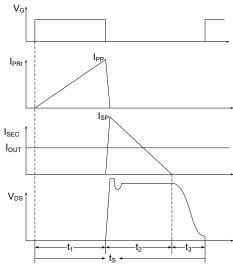


Fig.8 Switching waveforms

When the operation condition is with minimum input AC RMS voltage and full load, the switching frequency is minimum frequency, the maximum peak current through MOSFET and the transformer happens.

Once the minimum frequency  $f_{S\_MIN}$  is set, the inductance of the transformer could be induced. The design flow is shown as below:

(a) Select N<sub>PS</sub>;

$$N_{PS} \le \frac{V_{MOS\_(BR)DS} \times 80\% - \sqrt{2}V_{AC\_MAX} - \Delta V_{S}}{V_{OUT} + V_{DF}}$$
(11)

- (b) Preset minimum frequency f<sub>S\_MIN</sub>;
- (c) Compute inductor  $L_M$  and maximum primary peak current  $I_{P\_PK\_MAX}$ ;

$$\begin{split} I_{P\_PK\_MAX} &= \frac{2P_{OUT}}{\eta \times V_{DC\_MIN}} + \frac{2P_{OUT}}{\eta \times N_{PS} \times (V_{OUT} + V_{D\_F})} \\ &+ \pi \sqrt{\frac{2P_{OUT}}{\eta} \times C_{Drain} \times f_{S\_MIN}} \end{split} \tag{12}$$

$$L_{\rm M} = \frac{2P_{\rm OUT}}{\eta \times I_{\rm P~PK~MAX}^2 \times f_{\rm S~MIN}}$$
 (13)

Where,  $C_{Drain}$  is the parasitic capacitance at drain of integrated MOSFET;  $\eta$  is the efficiency;  $P_{OUT}$  is rated full load power;  $V_{DC\_MIN}$  is minimum input DC RMS voltage.

(d) Compute current rising time  $t_1$  and current falling time  $t_2$ ;

$$t_{1} = \frac{L_{M} \times I_{P\_PK\_MAX}}{V_{DC\_MIN}} (14)$$

$$t_2 = \frac{L_{\text{M}} \times I_{\text{P\_PK\_MAX}}}{N_{\text{PS}} \times (V_{\text{OUT}} + V_{\text{D.F.}})}$$
 (15)

$$t_{s} = \frac{1}{f_{s\_MIN}}$$
 (16)

(e) Compute primary maximum RMS current I<sub>P\_RMS\_MAX</sub> for the transformer fabrication;

$$I_{P_{-RMS_{-}MAX}} = \frac{\sqrt{3}}{3} I_{P_{-}PK_{-}MAX} \times \sqrt{\frac{t_{1}}{t_{s}}}$$
 (17)

(f) Compute secondary maximum peak current  $I_{S\_PK\_MAX}$  and RMS current  $I_{S\_RMS\_MAX}$  for the transformer fabrication.

$$I_{S PK MAX} = N_{PS} \times I_{P PK MAX}$$
 (18)

$$I_{S_{-RMS_{-}MAX}} = \frac{\sqrt{3}}{3} N_{PS} \times I_{P_{-}PK_{-}MAX} \times \sqrt{\frac{t_2}{t_S}}$$
 (19)

Transformer design (N<sub>P</sub>, N<sub>S</sub>, N<sub>AUX</sub>)



The design of the transformer is similar with ordinary Flyback transformer. The parameters below are necessary:

Necessary parameters	
Turns ratio	N <sub>PS</sub>
Inductance	$L_{M}$
Primary maximum current	$I_{P\_PK\_MAX}$
Primary maximum RMS current	I <sub>P_RMS_MAX</sub>
Secondary maximum RMS current	I <sub>S_RMS_MAX</sub>

The design rules are as followed:

- (a) Select the magnetic core style, identify the effective area  $A_e$ ;
- (b) Preset the maximum magnetic flux  $\Delta B$ ;

$$\Delta B = 0.22 \sim 0.26 T$$

(c) Compute primary turn N<sub>P</sub>;

$$N_{P} = \frac{L_{M} \times I_{P\_PK\_MAX}}{\Delta B \times A_{e}} (20)$$

(d) Compute secondary turn N<sub>S</sub>;

$$N_{\rm S} = \frac{N_{\rm P}}{N_{\rm ps}} (21)$$

(e) Compute auxiliary turn N<sub>AUX</sub>;

$$N_{AUX} = N_S \times \frac{V_{VIN}}{V_{OUT}}$$
 (22)

Where  $V_{VIN}$  is the working voltage of VIN pin (11V~15V is recommended);

(f) Select an appropriate wire diameter;

With  $I_{P\_RMS\_MAX}$  and  $I_{S\_RMS\_MAX}$ , select appropriate wire to make sure the current density ranges from  $4A/mm^2$  to  $10A/mm^2$ .

(g) If the winding area of the core and bobbin is not enough, reselect the core style, go to (a) and redesign the transformer until the ideal transformer is achieved.

### Input capacitor C<sub>BUS</sub>

Generally, the input capacitor C<sub>BUS</sub> is selected by

$$C_{BUS} = 2 \sim 3 \mu F/W$$

Or more accurately by

$$C_{BUS} = \frac{\arcsin(1 - \frac{V_{DC\_MIN}}{\sqrt{2}V_{AC\_MIN}}) + \frac{\pi}{2}}{\pi} \frac{P_{OUT}}{\eta} \frac{1}{2f_{IN}V_{AC\_MIN}^2(1 - \frac{V_{DC\_MIN}}{\sqrt{2}V_{AC\_MIN}})^2}$$
(23)

Where  $V_{DC\_MIN}$  is the minimum voltage of BUS line;  $f_{IN}$  is AC line frequency;

### **RCD** snubber for MOSFET

The power loss of the snubber P<sub>RCD</sub> is evaluated first.

$$P_{\text{RCD}} = \frac{N_{\text{PS}} \times (V_{\text{OUT}} + V_{\text{D\_F}}) + \Delta V_{\text{S}}}{\Delta V_{\text{S}}} \times \frac{L_{\text{K}}}{L_{\text{M}}} \times P_{\text{OUT}} (24)$$

Where  $N_{PS}$  is the turns ratio of the Flyback transformer;  $V_{OUT}$  is the output voltage;  $V_{D\_F}$  is the forward voltage of the power diode;  $\Delta V_S$  is the overshoot voltage clamped by RCD snubber;  $L_K$  is the leakage inductor;  $L_M$  is the inductance of the Flyback transformer;  $P_{OUT}$  is the output power.

The  $R_{RCD}$  is related with the power loss:

$$R_{RCD} = \frac{\left[N_{PS} \times (V_{OUT} + V_{D_{\perp}F}) + \Delta V_{S}\right]^{2}}{P_{RCD}}$$
 (25)

The  $C_{RCD}$  is related with the voltage ripple of the snubber  $\Delta V_{C\_RCD}$ :

$$C_{RCD} = \frac{N_{PS} \times (V_{OUT} + V_{D_{\_F}}) + \Delta V_{S}}{R_{RCD} \times f_{S\_MIN} \times \Delta V_{C\_RCD}}$$
(26)

# Layout

- (a) To achieve better EMI performance and reduce line frequency ripples, the output of the bridge rectifier should be connected to the BUS line capacitor first, then to the switching circuit;
- (b) The ground of the BUS line capacitor, the ground of the current sample resistor and the signal ground of the IC should be connected in a star connection;
- (c) The circuit loop of all switching circuit should be kept small: primary power loop, secondary loop and auxiliary power loop.



# **Design Notice**

- 1. VIN voltage prefer to larger than 11V for all conditions.
- 2. Some transformers structure may induce larger spike or larger ring on the current sample resistor at the initial of the primary switch turning on. This spike or ring may cause wrongly detection of the peak current and make the switch turn off earlier, so the accuracy feedback voltage sample cannot be guaranteed. The recommend structures are:0.5Primary.----Shielding----Second.----Auxiliary.----O.5Primary.or Primary.----Shielding-----Second.-----Auxiliary; Do not use the structure like 0.5Primary.----Auxiliary-----Second.-----Shielding.----0.5Primary.
- 3. Because IC built in CC/CV loop, in order to ensure the stability, output capacitor should be in a range, that is Co ut\*(Vo/Io) should not be far away from 3.7m.For example, 5V2Aoutput case, Cout=3.7/2.5=1480uF, the output c apacitor should be in the range of 1270uF to 1680uF. In other hand, switching frequency ripple should also be considerd. If switching frequency ripple is large, increase the capacitance properly or use low ESR capacitor.



# **Design Example**

A design example of typical application is shown below step by step.

### **#1.** Identify Design Specification

Design Specification			
V <sub>AC_MIN</sub>	90V	V <sub>AC_MAX</sub>	264V
V <sub>OUT</sub>	12V	I <sub>OUT</sub>	1A
P <sub>OUT</sub>	12W	η	85%
f <sub>S_MIN</sub>	55kHz	$\Delta V_{BUS}$	30% V <sub>BUS_MIN</sub>

#2.Transformer Design  $(N_{PS} \text{ and } L_M)$ 

### Refer to Power **Device Design**

Conditions					
V <sub>AC_MIN</sub>	90V	V <sub>AC_MAX</sub>	264V		
P <sub>OUT</sub>	12W	f <sub>S_MIN</sub>	55kHz		
Parameters designed	Parameters designed				
V <sub>MOS_(BR)DS</sub>	700V	$\Delta V_{S}$	75V		
C <sub>Drain</sub>	100pF	$V_{D_{\_}F}$	1V		

(a)Compute turns ratio N<sub>PS</sub> first;

$$\begin{split} N_{PS} & \leq \frac{V_{MOS\_(BR)DS} \times 80\% \text{-}\sqrt{2}V_{AC\_MAX} \text{-}\Delta V_{S}}{V_{OUT} \text{+}V_{D\_F}} \\ & = \frac{700V \times 0.8 \text{-}\sqrt{2} \times 264V \text{-}75V}{12V \text{+}1V} \\ & = 8.58 \end{split}$$

 $N_{\text{PS}}$  is set to

$$N_{PS} = 7$$

(b)f<sub>S MIN</sub> is preset;

$$f_{S\_MIN} = 55kHz$$

(c) Compute inductor  $L_M$  and maximum primary peak current  $I_{P\_PK\_MAX}$ ;

$$\begin{split} I_{P\_PK\_MAX} &= \frac{2P_{OUT}}{\eta \times \left(\sqrt{2}V_{AC\_MIN} - \Delta V_{BUS}\right)} + \frac{2P_{OUT}}{\eta \times N_{PS} \times (V_{OUT} + V_{D\_F})} + \pi \sqrt{\frac{2P_{OUT}}{\eta}} \times C_{Drain} \times f_{S\_MIN} \\ &= \frac{2 \times 12W}{0.85 \times (\sqrt{2} \times 90V - 0.3 \times \sqrt{2} \times 90V)} + \frac{2 \times 12W}{0.85 \times 7 \times (12V + 1V)} + \pi \times \sqrt{\frac{2 \times 12W}{0.85} \times 100pF \times 55kHz} \\ &= 0.666A \end{split}$$



$$\begin{split} L_{M} &= \frac{2P_{OUT}}{\eta \times I_{P\_PK\_MAX}^{2} \times f_{S\_MIN}} \\ &= \frac{2 \times 12W}{0.85 \times (0.666A)^{2} \times 55kHz} \\ &= 1.156mH \end{split}$$

Set

 $L_M=1.15mH$ 

(d) Compute current rising time  $t_1$  and current falling time  $t_2$ ;

$$t_{_{1}} = \frac{L_{_{M}} \times I_{_{P\_PK\_MAX}}}{\sqrt{2} V_{_{AC\_MIN}}} = \frac{1.15 mH \times 0.666 A}{\sqrt{2} \times 90 V} = 6.021 \mu s$$

$$t_{2} = \frac{L_{_{M}} \times I_{_{P\_PK\_MAX}}}{N_{_{PS}} \times (V_{_{OUT}} + V_{_{D\_F}})} = \frac{1.15 \text{mH} \times 0.666 \text{A}}{5 \times (12 \text{V} + 1 \text{V})} = 8.421 \mu \text{s}$$

$$t_3 = \pi \times \sqrt{L_M \times C_{Drain}} = \pi \times \sqrt{1.15 \text{mH} \times 100 \text{pF}} = 1.065 \mu \text{s}$$

$$t_s = t_1 + t_2 + t_3 = 6.021 \mu s + 8.421 \mu s + 1.065 \mu s = 15.51 \mu s$$

(e) Compute primary maximum RMS current I<sub>P\_RMS\_MAX</sub> for the transformer fabrication;

$$I_{P\_RMS\_MAX} = \frac{\sqrt{3}}{3} I_{P\_PK\_MAX} \times \sqrt{\frac{t_1}{t_S}} = \frac{\sqrt{3}}{3} \times 0.666 A \times \sqrt{\frac{6.021 \mu s}{15.51 \mu s}} = 0.24 A$$

(f) Compute secondary maximum peak current  $I_{S\_PK\_MAX}$  and RMS current  $I_{S\_RMS\_MAX}$  for the transformer fabrication.

$$I_{S\_PK\_MAX} = N_{PS} \times I_{P\_PK\_MAX} = 7 \times 0.666A = 4.662A$$

$$I_{S\_RMS\_MAX} = N_{PS} \times \frac{\sqrt{3}}{3} I_{P\_PK\_MAX} \times \sqrt{\frac{t_2}{t_s}} = 7 \times \frac{\sqrt{3}}{3} \times 0.666 A \times \sqrt{\frac{8.421 \mu s}{15.51 \mu s}} = 1.984 A$$

#3. Select secondary power diode

### Refer to **Power Device Design**

Compute the voltage and the current stress of secondary power diode

$$V_{D_{\_R\_MAX}} = \frac{\sqrt{2}V_{AC\_MAX}}{N_{PS}} + V_{OUT}$$
$$= \frac{\sqrt{2} \times 264V}{7} + 12V$$
$$= 65.3V$$

 $I_{D_{PK\_MAX}} = N_{PS} \times I_{P_{PK\_MAX}} = 7 \times 0.666A = 4.662A$ 



$$I_{D\_AVG} = I_{OUT} = 1A$$

## #4. Start up design

### Refer to Start up

Conditions				
V <sub>DC_MIN</sub>	90V × 1.414	$V_{DC\_MAX}$	264V×1.414	
I <sub>ST</sub>	1.2μA (typical)	V <sub>IN_ON</sub>	14.7V (typical)	
I <sub>VIN_OVP</sub>	9mA (typical)	I <sub>HV_ON</sub>	0.35mA (typical)	
I <sub>HV_OFF</sub>	5μA (typical)			
Designed by user				
$t_{ST}$	1s			

### (a) Design C<sub>VIN</sub>

$$\begin{split} C_{\text{VIN}} &= \frac{(I_{\text{HV\_ON}} - I_{\text{HV\_OFF}} - I_{\text{ST}}) \times t_{\text{ST}}}{V_{\text{VIN\_ON}}} \\ &= \frac{(0.35*10^3 - 5 - 1.2) \times 1s}{14.7V} \\ &= 23.38 \mu F \end{split}$$

Set

$$C_{\text{VIN}} = 22 \mu F$$

### **#5**. Output voltage control

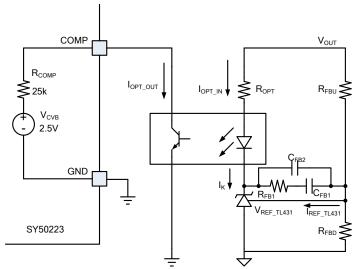


Fig.9 Output voltage feedback circuit

Conditions			
$V_{CVB}$	2.5V	V <sub>COMP_ON</sub>	0.4V
R <sub>COMP</sub>	25kΩ	V <sub>OPT</sub>	1.2V
β	1	V <sub>REF_TL431</sub>	2.5V



I <sub>K_MIN</sub>	1mA	$I_{K\_MAX}$	100mA
I <sub>REF_TL431</sub>	2~4μΑ		

Where  $V_{OPT}$  is the input forward voltage of the opto-coupler;  $I_K$  is the cathode current of the TL431;  $I_{REF\_TL431}$  is the reference input current of the TL431.

## (a) R<sub>OPT</sub> Design

The maximum input current of the opto-coupler is limited by

$$\begin{split} I_{OPT\_IN\_MAX} &> \frac{V_{CVB} \text{--}V_{COMP\_ON}}{R_{COMP}} \times \frac{1}{\beta} \\ &= \frac{2.5 \text{V-}0.4 \text{V}}{25 \text{K}\Omega} \times 1 \\ &= 0.084 \text{mA} \end{split}$$

At the same time,

 $I_{OPT\ IN}$  is limited by the current range of TL431 cathode .

$$I_{\text{K\_MAX}}{>}I_{\text{OPT\_IN}}{>}I_{\text{K\_MIN}}$$

And

$$I_{OPT\_IN}\!=\!\frac{V_{OUT}\!-\!V_{OPT}\!-\!V_{REF\_TL431}}{R_{OPT}}$$

Hence,

$$\begin{split} R_{OPT} < & \frac{V_{OUT} \text{--}V_{OPT} \text{--}V_{REF\_TL431}}{I_{OPT\_IN\_MAX}} \\ = & \frac{12V \text{--}1.2V \text{--}2.5V}{0.084mA} \\ = & 98.8k\Omega \end{split}$$

$$\begin{split} R_{OPT} &> \frac{V_{OUT}\text{-}V_{OPT}\text{-}V_{REF\_TL431}}{I_{K\_MAX}} \\ &= \frac{12V\text{-}1.2V\text{-}2.5V}{100mA} \\ &= 83\Omega \end{split}$$

Set

$$R_{OPT} = 1k\Omega$$

#### (b) Resistor divider design

To achieve accurate voltage reference, R<sub>FBD</sub> is limited by

$$R_{_{FBD}} \leq \! \frac{V_{_{REF\_TL431}}}{100\!\times\!I_{_{REF\_TL431}}} \! = \! \frac{2.5V}{100\!\times\!2\mu A} \! = \! 12.5K\Omega$$



Set

$$R_{_{FBD}}\!=\!\!10k\Omega$$

$$R_{_{FBU}} \!=\! \frac{V_{_{OUT}} \!-\! V_{_{REF\_TL431}}}{V_{_{REF\_TL431}}} \!\times\! R_{_{FBD}} \!=\! \frac{12V \!-\! 2.5V}{2.5V} \!\times\! 10k\Omega \!=\! 38k\Omega$$

Set

$$R_{FBD} = 39k\Omega$$

### (c) Feedback Loop Design

Recommended parameters			
$C_{FB1}$	100nF	C <sub>FB2</sub>	0pF
R <sub>FB1</sub>	100kΩ		

### #6. Output Current Protection Design

Conditions				
$\mathbf{k}_1$	0.5	$K_2$	1	
$V_{REF}$	0.42V	N <sub>PS</sub>	7	
Parameters designed				
I <sub>OUT_LIM</sub>	1.15A			

 $I_{\text{OUT\_LIM}}$  is the maximum output current .

The current sense resistor is

$$\begin{split} R_{\text{S}} &= \frac{k_{\text{1}} \times V_{\text{REF}} \times N_{\text{PS}}}{I_{\text{OUT\_LIM}}} \\ &= \frac{0.5 \times 0.42 V \times 7}{1.15 A} \\ &= 1.278 \Omega \end{split}$$

Set  $R_S=1.3 \Omega$ 

### #7. Input Capacitor C<sub>BUS</sub> Design

Conditions			
V <sub>AC_MIN</sub>	90V	$\Delta V_{BUS}$	30% V <sub>BUS_MIN</sub>



$$C_{BUS} = \frac{\arcsin(1 - \frac{\Delta V_{BUS}}{\sqrt{2}V_{AC\_MIN}}) + \frac{\pi}{2}}{\pi} \times \frac{P_{OUT}}{\eta} \times \frac{1}{2f_{IN}V_{AC\_MIN}^2[1 - (1 - \frac{\Delta V_{BUS}}{\sqrt{2}V_{AC\_MIN}})^2]}$$

$$\arcsin(1 - \frac{0.3 \times \sqrt{2} \times 90V}{\pi}) + \frac{\pi}{2} \times \frac{1}{2f_{IN}V_{AC\_MIN}^2[1 - (1 - \frac{\Delta V_{BUS}}{\sqrt{2}V_{AC\_MIN}})^2]}$$

$$= \frac{\arcsin(1 - \frac{0.3 \times \sqrt{2} \times 90V}{\sqrt{2} \times 90V}) + \frac{\pi}{2}}{\pi} \times \frac{12W}{0.85} \times \frac{1}{2 \times 50 \text{Hz} \times 90V^2 \times [1 - (1 - \frac{0.3 \times \sqrt{2} \times 90V}{\sqrt{2} \times 90V})^2]}$$

$$=25.52\mu F$$

$$C_{\text{BUS}} = 25 \, \mu F$$

### #8. Set VSEN pin

First identify R<sub>VSENU</sub> need for line regulation.

Conditions				
$k_3$	68			
Parameters Designed				
R <sub>VSENU</sub>	91kΩ			

Then compute R<sub>VSEND</sub>

Conditions				
V <sub>VSEN_OVP</sub>	1.45V			
$V_{OUT}$	12V			
Parameters designed				
V <sub>OVP</sub>	14V	R <sub>VSENU</sub>	91kΩ	
N <sub>S</sub> /N <sub>AUX</sub>	15/16			

$$R_{\text{VSEND}} = \frac{\frac{V_{\text{VSEN\_OVP}}}{V_{\text{OVP}}} \times \frac{N_{\text{S}}}{N_{\text{AUX}}}}{1 - \frac{V_{\text{VSEN\_OVP}}}{V_{\text{OVP}}} \times \frac{N_{\text{S}}}{N_{\text{AUX}}}} \times R_{\text{ZCSU}}$$

$$= \frac{\frac{1.45 \text{V}}{14 \text{V}} \times \frac{15}{16}}{1 - \frac{1.45 \text{V}}{14 \text{V}} \times \frac{15}{16}} \times 91 \text{k}\Omega$$

$$= 9.78 \text{k}\Omega$$

Set R<sub>VSEND</sub> = 9.1k

### #9. Design RCD snubber

### Refer to **Power Device Design**

Conditions			
$V_{OUT}$	12V	$\Delta V_{S}$	75V
N <sub>PS</sub>	7	$L_{K}/L_{M}$	1%
Pout	12W		



The power loss of the snubber is

$$\begin{split} P_{\text{RCD}} &= \frac{N_{\text{PS}} \times (V_{\text{OUT}} + V_{\text{D\_F}}) + \Delta V_{\text{S}}}{\Delta V_{\text{S}}} \times \frac{L_{\text{K}}}{L_{\text{M}}} \times P_{\text{OUT}} \\ &= \frac{7 \times (12V + 1V) + 75V}{75V} \times 0.01 \times 12W \\ &= 0.266W \end{split}$$

The resistor of the snubber is

$$\begin{split} R_{RCD} = & \frac{\left[N_{PS} \times (V_{OUT} + V_{D\_F}) + \Delta V_{S}\right]^{2}}{P_{RCD}} \\ = & \frac{\left[7 \times (12V + 1V) + 75V\right]^{2}}{0.266W} \\ = & 103.6k\Omega \end{split}$$

Set  $R_{RCD} = 200K$ 

The capacitor of the snubber is

$$\begin{split} C_{\text{RCD}} &= \frac{N_{\text{PS}} \times (V_{\text{OUT}} + V_{\text{D\_F}}) + \Delta V_{\text{S}}}{R_{\text{RCD}} f_{\text{S\_MIN}} \Delta V_{\text{C\_RCD}}} \\ &= \frac{7 \times (12 \text{V} + 1 \text{V}) + 75 \text{V}}{200 \text{k} \Omega \times 55 \text{kHz} \times 25 \text{V}} \\ &= 604 \text{pF} \end{split}$$

Set  $C_{RCD} = 680 pF$ 

### #10. Final Result

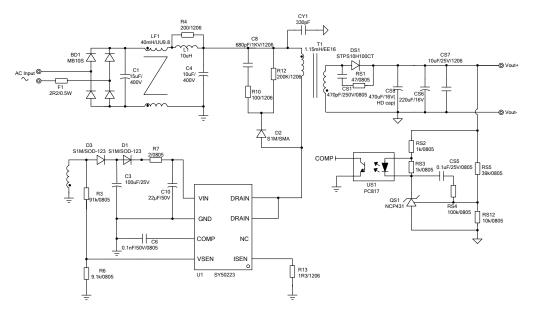
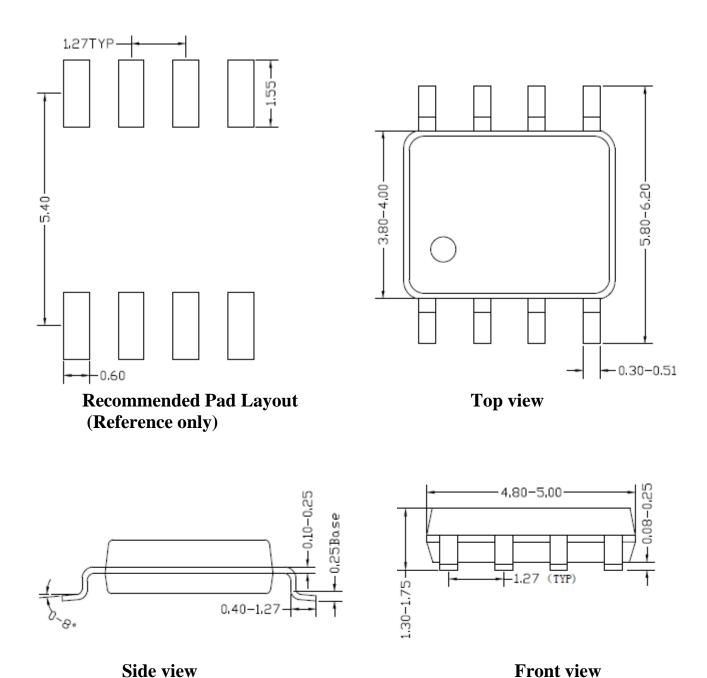


Fig.10 Final Result



# **SO8 Package Outline & PCB Layout Design**

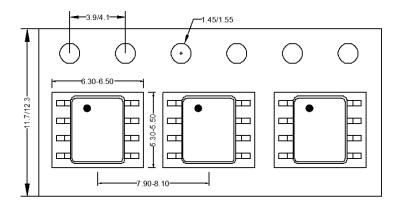


Notes: All dimension in millimeter and exclude mold flash & metal burr.



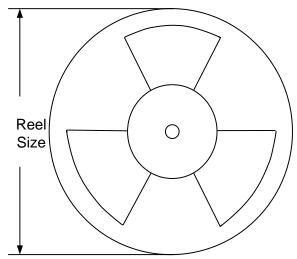
# **Taping & Reel Specification**

# 1. Taping orientation for packages (SO8)



Feeding direction ----

# 2. Carrier Tape & Reel specification for packages



Package type	Tape width (mm)	Pocket pitch(mm)	Reel size (Inch)	Trailer length(mm)	Leader length (mm)	Qty per reel
SO8	12	8	13"	400	400	2500



#### IMPORTANT NOTICE

- 1. **Right to make changes.** Silergy and its subsidiaries (hereafter Silergy) reserve the right to change any information published in this document, including but not limited to circuitry, specification and/or product design, manufacturing or descriptions, at any time and without notice. This document supersedes and replaces all information supplied prior to the publication hereof. Buyers should obtain the latest relevant information before placing orders and should verify that such information is current and complete. All semiconductor products are sold subject to Silergy's standard terms and conditions of sale.
- 2. Applications. Application examples that are described herein for any of these products are for illustrative purposes only. Silergy makes no representation or warranty that such applications will be suitable for the specified use without further testing or modification. Buyers are responsible for the design and operation of their applications and products using Silergy products. Silergy or its subsidiaries assume no liability for any application assistance or designs of customer products. It is customer's sole responsibility to determine whether the Silergy product is suitable and fit for the customer's applications and products planned. To minimize the risks associated with customer's products and applications, customer should provide adequate design and operating safeguards. Customer represents and agrees that it has all the necessary expertise to create and implement safeguards which anticipate dangerous consequences of failures, monitor failures and their consequences, lessen the likelihood of failures that might cause harm and take appropriate remedial actions. Silergy assumes no liability related to any default, damage, costs or problem in the customer's applications or products, or the application or use by customer's third-party buyers. Customer will fully indemnify Silergy, its subsidiaries, and their representatives against any damages arising out of the use of any Silergy components in safety-critical applications. It is also buyers' sole responsibility to warrant and guarantee that any intellectual property rights of a third party are not infringed upon when integrating Silergy products into any application. Silergy assumes no responsibility for any said applications or for any use of any circuitry other than circuitry entirely embodied in a Silergy product.
- 3. **Limited warranty and liability.** Information furnished by Silergy in this document is believed to be accurate and reliable. However, Silergy makes no representation or warranty, expressed or implied, as to the accuracy or completeness of such information and shall have no liability for the consequences of use of such information. In no event shall Silergy be liable for any indirect, incidental, punitive, special or consequential damages, including but not limited to lost profits, lost savings, business interruption, costs related to the removal or replacement of any products or rework charges, whether or not such damages are based on tort or negligence, warranty, breach of contract or any other legal theory. Notwithstanding any damages that customer might incur for any reason whatsoever, Silergy' aggregate and cumulative liability towards customer for the products described herein shall be limited in accordance with the Standard Terms and Conditions of Sale of Silergy.
- 4. **Suitability for use.** Customer acknowledges and agrees that it is solely responsible for compliance with all legal, regulatory and safety-related requirements concerning its products, and any use of Silergy components in its applications, notwithstanding any applications-related information or support that may be provided by Silergy. Silergy products are not designed, authorized or warranted to be suitable for use in life support, life-critical or safety-critical systems or equipment, nor in applications where failure or malfunction of an Silergy product can reasonably be expected to result in personal injury, death or severe property or environmental damage. Silergy assumes no liability for inclusion and/or use of Silergy products in such equipment or applications and therefore such inclusion and/or use is at the customer's own risk.
- 5. **Terms and conditions of commercial sale**. Silergy products are sold subject to the standard terms and conditions of commercial sale, as published at http://www.silergy.com/stdterms, unless otherwise agreed in a valid written individual agreement specifically agreed to in writing by an authorized officer of Silergy. In case an individual agreement is concluded only the terms and conditions of the respective agreement shall apply. Silergy hereby expressly objects to and denies the application of any customer's general terms and conditions with regard to the purchase of Silergy products by the customer.
- 6. No offer to sell or license. Nothing in this document may be interpreted or construed as an offer to sell products that is open for acceptance or the grant, conveyance or implication of any license under any copyrights, patents or other industrial or intellectual property rights. Silergy makes no representation or warranty that any license, either express or implied, is granted under any patent right, copyright, mask work right, or other intellectual property right. Information published by Silergy regarding third-party products or services does not constitute a license to use such products or services or a warranty or endorsement thereof. Use of such information may require a license from a third party under the patents or other intellectual property of the third party, or a license from Silergy under the patents or other intellectual property of Silergy.

For more information, please visit: www.silergy.com

© 2018 Silergy Corp.

All Rights Reserved.